

Multi-input 1 (FOR function)

Multi-input 2 (REV function)

Multi-input 3 (RST function)

Multi-input 4 (SPH function)

Multi-input 5 (SPM function)

Multi-input 6 (SPL function)

Set Range: 00—32 Unit: No

control modes.

Jogging

fault signals

Forward Rotation

Reverse Rotation

Switching of FOR/REV rotation

Factory Setting: 02

Factory Setting: 10

Factory Setting: 17

Factory Setting: 18

Factory Setting: 19

Running. It can be combined with other terminals to compose multiple

Emergent stop. It can receive external emergent stop command or other

Reset. This terminal can be used for reset after a fault is removed.

The terminal is set for empty to prevent false actions.

Factory Setting:

PD044

PD045

PD046

PD047

PD048

00: Invalid.

01: RUN

02: FOR

03: REV

04: STOP

06: JOG

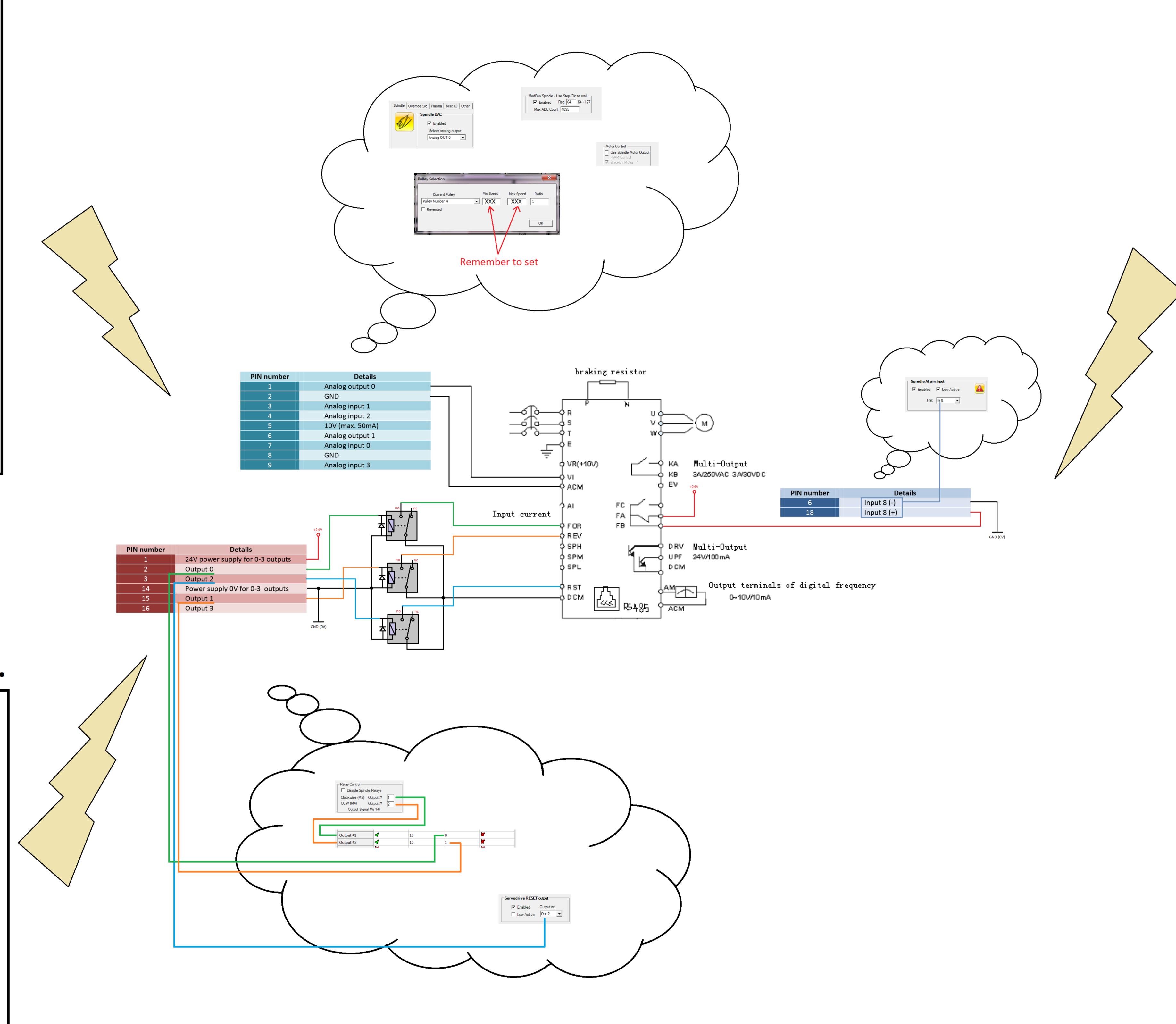
10: RST

05: FOR/REV

07: Jog FOR Rotation

08: Jog REV Rotation

09: Emergent Stop:



## 3.

8. Descript	ion of AutoPLC Clear Suspend:	
For details	refer to 10. Example Application of Aut	toPLC Suspend in Appendix 1 and the
description	of related parameters in PD117.	
* PD050	Multi-Output 1 (DRV function)	Factory Setting: 01**
* PD051	Multi-Output 2 (UPF function)	Factory Setting: 05
* PD052	Multi-Output 3 (FA, FB, FC function)	Factory Setting: 02

Note:

1 The above functions with the mark of \* are dedicated to the inverter of A series, which may be not available for P or J series.

Factory Setting: 00

02: Fault Indication: The contact will act when the inverter detects abnormal conditions.

Multi-Output 4 (KA, KB function)

Set Range: 00—32 Unit: 1